



RICE

# Wavelet-Based Deconvolution using Optimally Regularized Inversion for Ill-Conditioned Systems

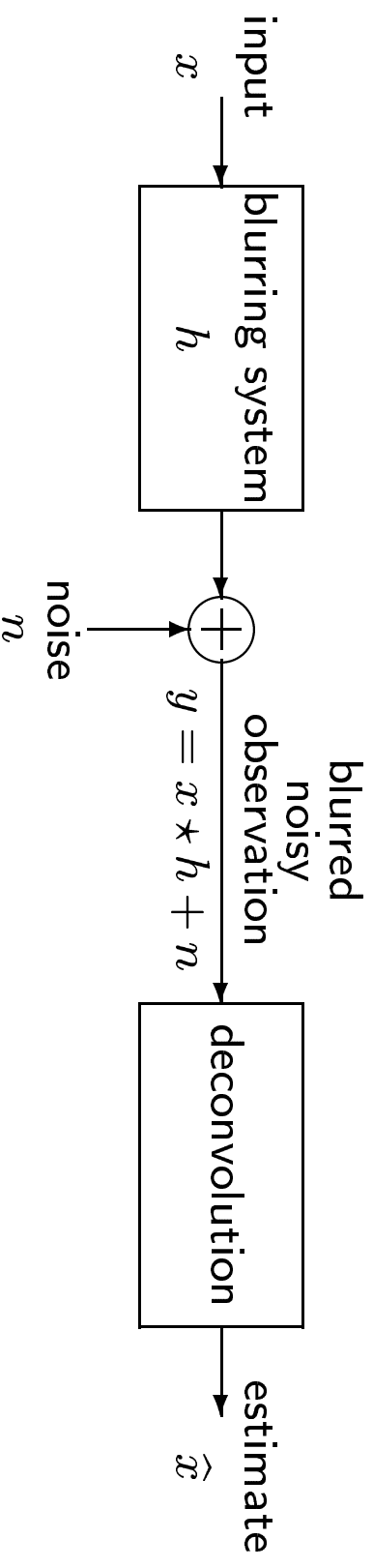
*Ramesh Neelamani, Hyeokho Choi, and Richard Baraniuk*

Rice University

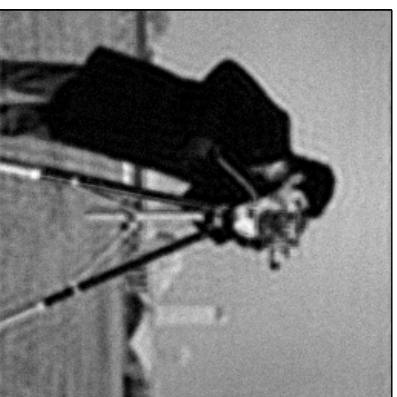
Supported by

Texas Instruments, National Science Foundation, DARPA/AFOSR  
Rice Consortium for Computational Seismic Interpretation

# Deconvolution



input



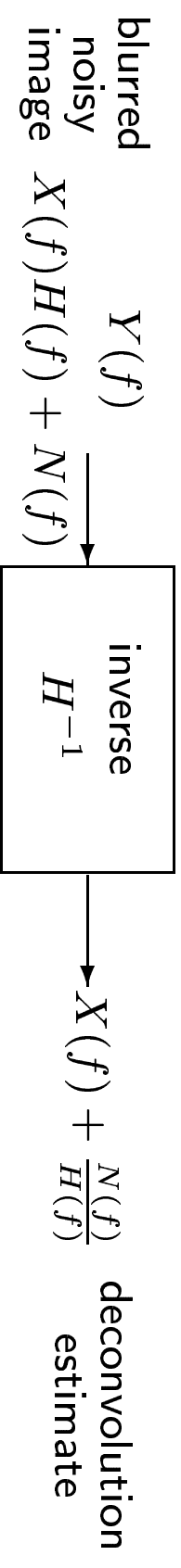
observed



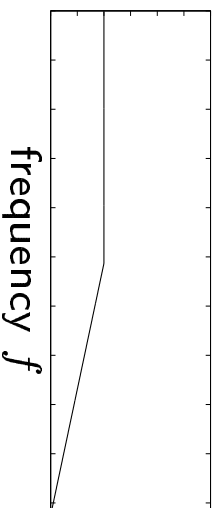
estimate

- Problem: given  $y$ ,  $h$ , find  $x$
- Applications: satellite imagery, seismic exploration, ...

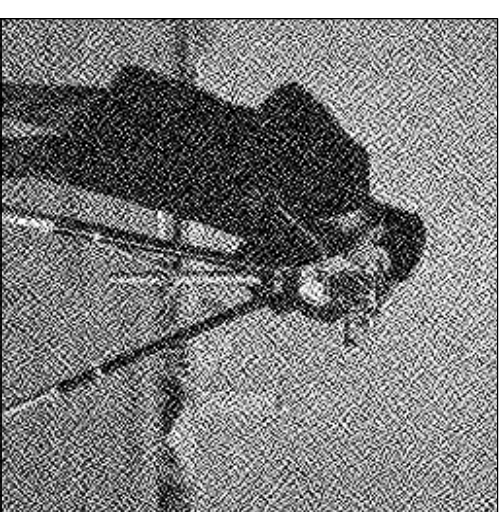
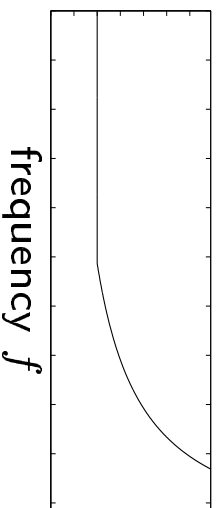
# Deconvolution is Ill-Posed



$|H(f)|$



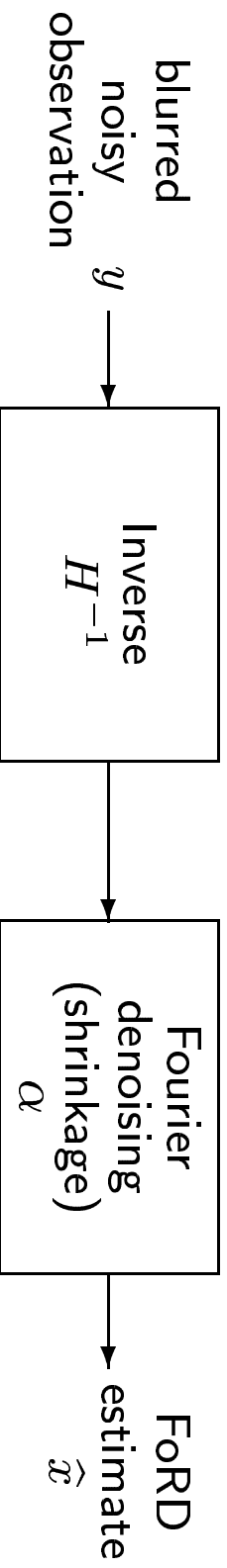
$|H^{-1}(f)|$



after pure inversion

- $|H(f)| \approx 0 \Rightarrow$  noise  $\frac{N(f)}{H(f)}$  explodes!
- Solution: *regularization* (approximate inversion)

## Fourier-domain Regularized Deconvolution (FoRD)



- Fourier transform diagonalizes  $H$

$\Rightarrow$  identifies and attenuates amplified noise frequency components

- Ex: Wiener filter (MSE-optimal LTI estimator)

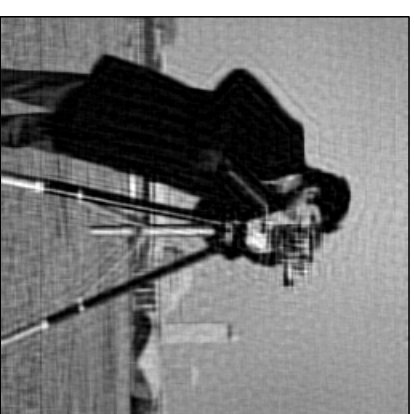
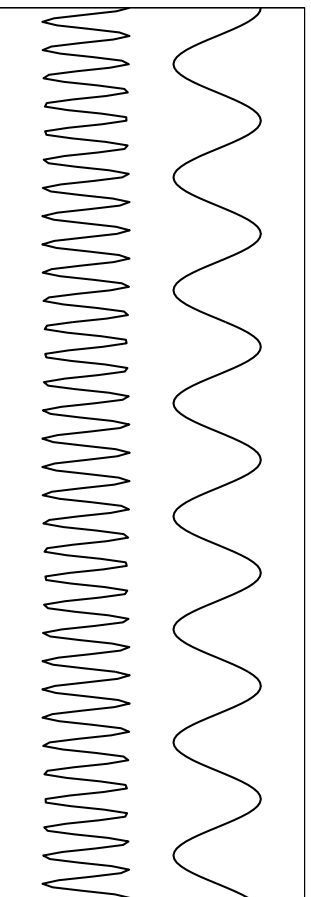
$$\hat{X}(f) = Y(f) \frac{1}{H(f)} \frac{|H(f)|^2 \text{SNR}(f)}{|H(f)|^2 \text{SNR}(f) + \alpha}$$

– SNR high  $\Rightarrow$  less shrinkage      SNR low  $\Rightarrow$  more shrinkage

- Inversion and shrinkage done together in practice

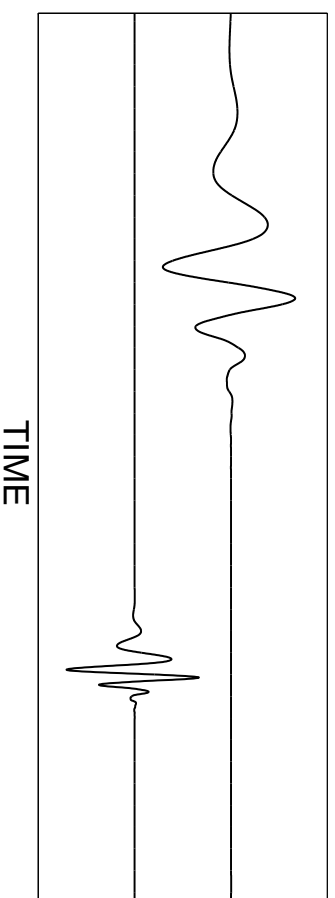
## Matchmaking

- Fourier basis: not suited for images with edges

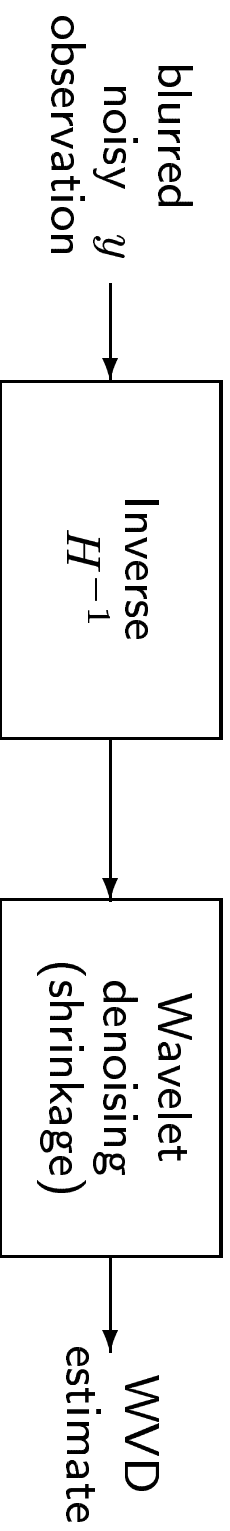


Wiener estimate


- Fourier basis: *matched* to operator but *unmatched* to signal
- Wavelets: *matched* to signal (economical representation)

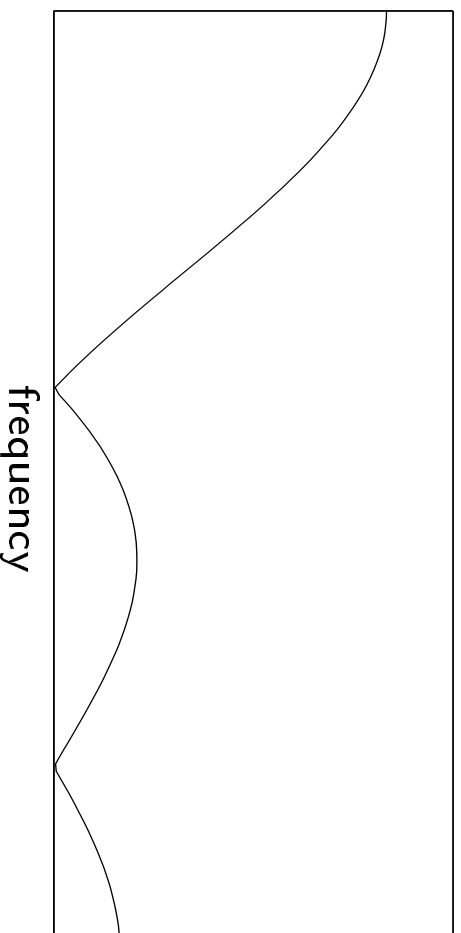


## Wavelet Vaguelette Deconvolution (WVD)

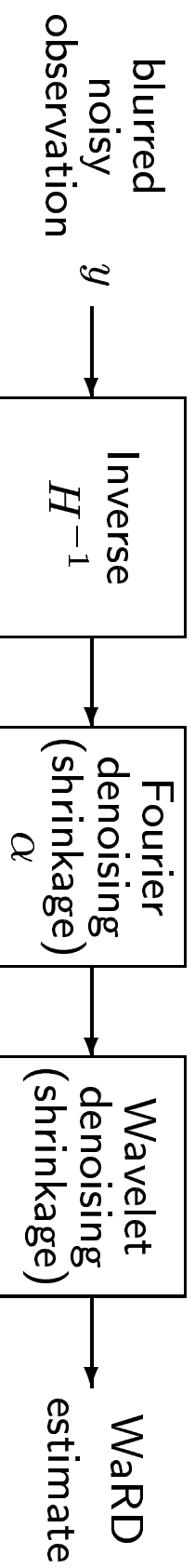


- Donoho '95: near optimal performance for *certain*  $H$
- Kalifa et al. '98: extended class of applicable  $H$
- Bottom line: do not apply to arbitrary  $H$

Ex:  blur

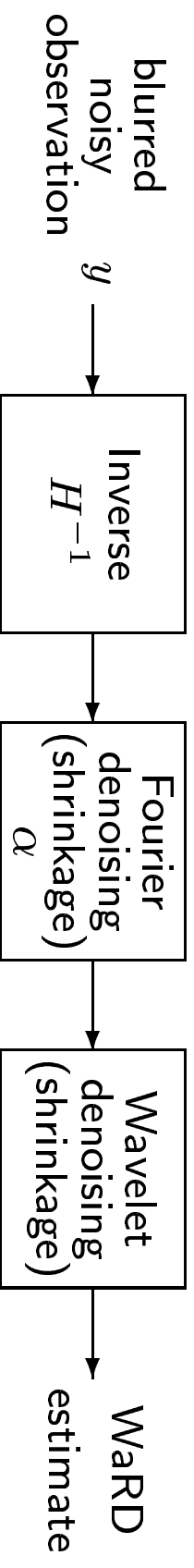


## Wavelet-domain Regularized Deconvolution (WaRD)



- Fourier denoising: exploits convolution operator structure
- Wavelet denoising: exploits input signal structure
- Choice of  $\alpha$ : balance Fourier and wavelet denoising
- Applicable to all convolution operators
- Simple and fast algorithm:  $O(M \log^2 M)$  for  $M$  pixels

## How Much Fourier Regularization?



- Tradeoff:

$$\alpha \text{ large} \Rightarrow \left\{ \begin{array}{l} \text{noise in wavelet domain reduced} \\ \text{edges smeared} \end{array} \right.$$
$$\alpha \text{ small} \Rightarrow \left\{ \begin{array}{l} \text{noise in wavelet domain increased} \\ \text{edges preserved} \end{array} \right.$$

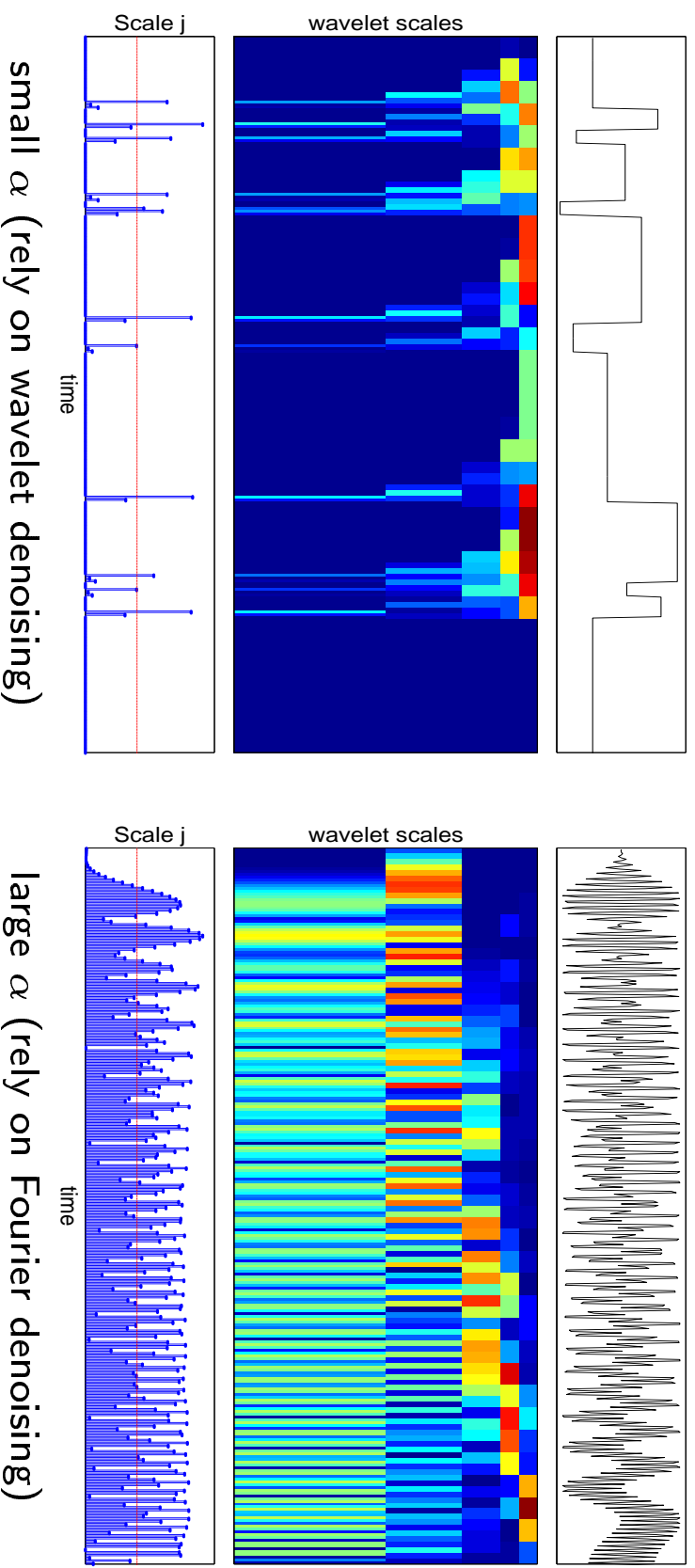
- Goal: balance Fourier and wavelet denoising
- Criterion: minimize overall MSE

$$\text{MSE} \approx \underbrace{\text{Fourier distortion error}}_{\text{Fourier distortion error}} + \underbrace{\text{wavelet thresholding error}}_{\text{wavelet thresholding error}}$$



## Optimal regularization $\alpha$

Optimal  $\alpha$  for  $\quad = \quad$  % of wavelet coeffs  $>$   
wavelet scale  $j$   $\quad$  noise variance in scale  $j$



Optimal balance controlled by economics of wavelet representation

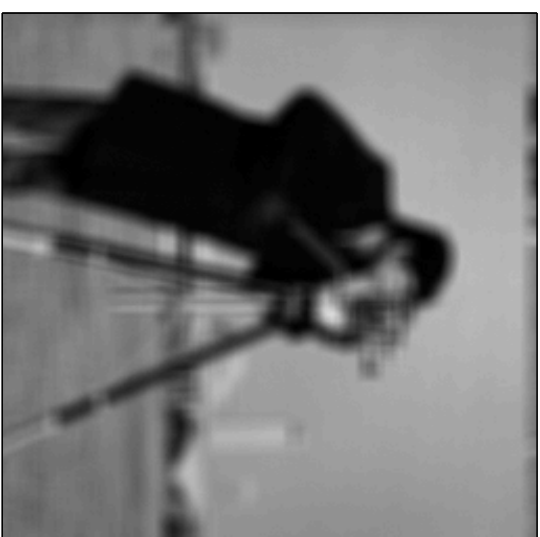
## Optimality of WaRD

- $\alpha = 0 \Rightarrow \text{WaRD} = \text{WVD}$ 
  - WaRD inherits asymptotic optimality from WVD
- Optimal  $\alpha \neq 0 \Rightarrow \text{WaRD}$  outperforms WVD (small samples)
- Optimal  $\alpha \ll 1$  (for most real world signals)
- WaRD applies for all convolution operators

Original



Observed



Wiener (SNR = 20.6 dB)

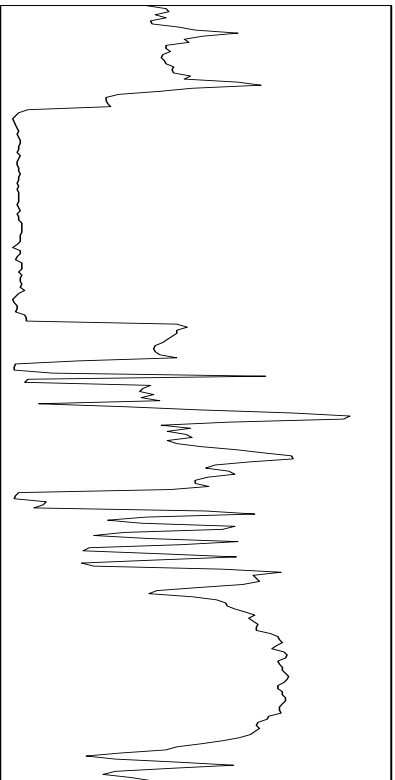


WaRD (SNR = 22.4 dB)

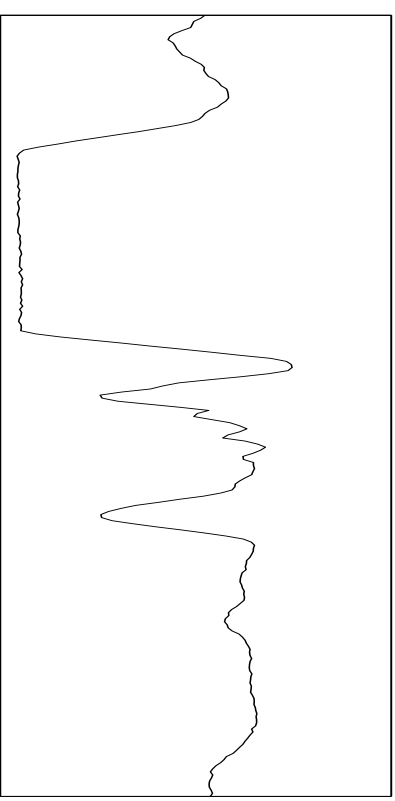


# Image Cross-Sections

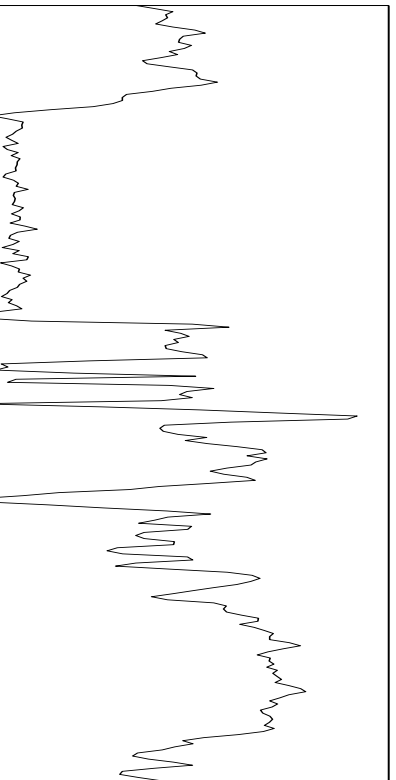
Original



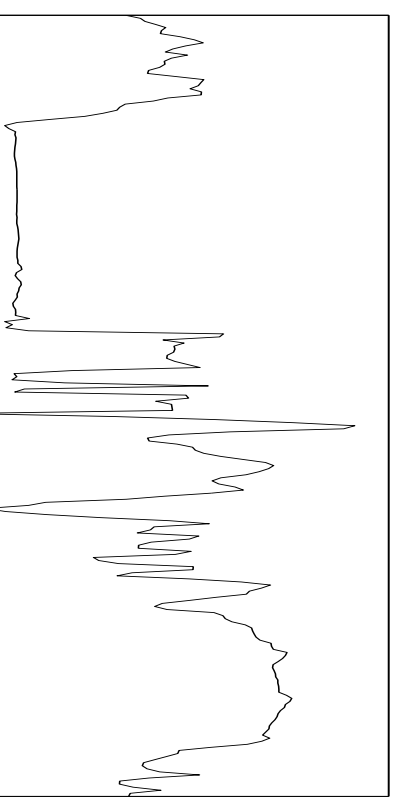
Observed



FoRD



WaRD



## Conclusions

- WaRD: Balances Fourier-domain and wavelet-domain denoising
- WaRD simultaneously preserves critical edges and smooth regions
- Simple and fast algorithm:  $O(M \log^2 M)$  for  $M$  pixels
- Near-optimal asymptotic performance  
Good small sample performance
- Applicable even when  $H$  not invertible
- Outperforms conventional WVD

Web: <http://www.dsp.rice.edu>