Flip-Flops

Objectives

This section is the first dealing with sequential circuits. It introduces Flip-Flops, an important building block for most sequential circuits.

- First it defines the most basic sequential building block, the RS latch, and investigates some of its properties.
- Then, it introduces clocks and shows how they can be used to synchronize latches to get gated latches.
- Finally, it extends gated latches to flip-flops by developing a more stable clocking technique called dynamic clocks.
- The Section also develops the state table behavioral model for gated latches and flip-flops

Reading Assignment

- Chapter 3, Sections 3.1-3.3.

Latches

Problem: Design a network to control a lamp from two pushbutton switches labeled S and R. If we push switch S the light should turn on. If we then release S, the light should stay on. If we push switch R, the lamp should turn off and stay off after releasing R. Assume that both S and R are not pushed at the same time.
A Solution

Construct a truth table for this circuit.

<table>
<thead>
<tr>
<th>R</th>
<th>S</th>
<th>X</th>
<th>Q</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0'</td>
<td>X'</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

Write Boolean expressions for X and Q.

\[ X = (S+Q)'; \quad Q = (R+X)' \]

\[ Q = R'\cdot X' = R'\cdot(S+Q) \]

Let \( S = R = 0 \). Then \( Q = 1\cdot(0+Q) = Q \)

The previous circuit is called an SR Latch and is usually drawn as shown below:

- Observations
  - The latch has two states, \( Q = 0 \) and \( Q = 1 \)
  - The output depends on the state as well as the inputs, so the circuit is sequential
  - The circuit has a loop, as all sequential circuits do
  - The outputs \( Q \) and \( Q_L \) are logical complements unless inputs \( S \) and \( R \) are both 1
  - Asserting \( S \) (i.e., setting it to 1) sets \( Q \) to 1 (and \( Q_L \) to 0).
  - Asserting \( R \) (i.e., setting it to 1) resets \( Q \) to 0 (and \( Q_L \) to 1)
  - If neither \( S \) nor \( R \) are asserted, \( Q \) retains a value determined by the last time \( S \) or \( R \) were asserted
  - Bad things can happen if both \( S \) and \( R \) are asserted simultaneously as we will see below.
Unstable latch behavior (Oscillation)

- Assume that all gates have a fixed delay $\delta$ modeled as follows:

$$
\begin{align*}
X &\quad \delta \quad Y \\
Y(t+\delta) &= X(t)
\end{align*}
$$

- This gives the following latch model:

$$
\begin{align*}
Q(t+\delta) \\
R &\quad \delta \quad Q(t) \\
S &\quad \delta \quad X(t) \\
X(t+\delta) &= X(t)
\end{align*}
$$

- Then $Q(t+\delta) = (R(t) + X(t))' = R(t)' \cdot X(t)'$, and $X(t+\delta) = (S(t) + Q(t))' = S(t)' \cdot Q(t)'$

Now set $S = R = 1$, so that both $Q$ and $X$ are equal to 0 after at most a delay of $\delta$. Then change both $R$ and $S$ to 0 at exactly the same time. Then

$$
Q(t+\delta) = X(t)' \quad \text{and} \quad X(t+\delta) = Q(t)'
$$
**Unstable latch behavior (Metastable state)**

- Equivalent circuit for the latch when \( R = S = 0 \)

![Equivalent circuit for the latch when \( R = S = 0 \)](image)

- Transfer characteristics of an inverter:

![Transfer characteristics of an inverter](image)

Now consider the behavior of the following circuit:

- Superimposing the two graphs gives the following:

![Superimposing the two graphs gives the following](image)
Now consider connecting \( v_{02} \) to \( v_{i1} \)

- The dots on the graph represent points where the inputs and outputs of the delays are equal.
- The dots on the two ends represent the two stable states of the system. Small changes in any of the signals are damped out quickly.
- The dot in the middle represents a metastable state. Small changes in any of the signals are amplified and the circuit leaves the metastable state.

- The hill analogy:
  - The latch could get in the metastable state in the following way:

- What is the relationship between hazards and the metastable state?

Avoiding unstable behavior of SR latches

- Since both the oscillation and the metastable state are undesirable behavior, we should try to avoid them. This can be done with the following rules:
  - Do not change \( R \) and \( S \) from 1 to 0 at the same time.
    - This is necessary to avoid the oscillation behavior seen above
    - One way to guarantee that this will not happen is to never allow them to both be 1 at the same time.
  - Once you change an input, do not change it again until the circuit has had time to complete all its signal transitions and reach a stable state.
    - This is necessary to avoid the metastable behavior illustrated above
/R/S Latch

Changing from 00 to 11 can produce nondeterministic behavior

Propagation Delay of Ungated Latches

$t_{PRQ}$ - Delay from the R input to the Q output
$t_{PSQ}$ - Delay from the S input to the Q output
$t_{PRQ,L}$ - Delay from the R input to the Q_L output
$t_{PSQ,L}$ - Delay from the S input to the Q_L output

Verilog descriptions of an SR latch

```verilog
module srlatch1 (s, r, q, q_n);
  input s, r;
  output q, q_n;
  assign q_n = ~(s | q);
  assign q = ~(r | q_n);
endmodule

module srlatch2 (s, r, q);
  input s, r;
  output q;
  reg q;
  always @(s or r)
    if (s & r) q = 0;
    else if (~s & r) q = 0;
    else if (s & ~r) q = 1;
endmodule

module srlatch3 (s, r, q);
  input s, r;
  output q;
  reg q;
  always @(s or r)
    case (s,r)
      3: q = 0;
      2: q = 1;
      1: q = 0;
    endcase
endmodule
```
Gated Latches

- Clock Signals
  - It is easier to avoid the metastable state if we place restrictions on when a latch can change states. This is usually done with a clock signal.
  - The effect of the clock is to define discrete time intervals.
  - The clock signal is used so that the latch inputs are ignored except when the clock signal is asserted.
  - This effectively makes time discrete, since we do not care what happens when the clock is not asserted.

Gated SR Latch

- Gated Latch Function Table

<table>
<thead>
<tr>
<th>CK</th>
<th>S</th>
<th>R</th>
<th>Q(t+δ)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>0</td>
<td>0</td>
<td>Q(t)</td>
</tr>
<tr>
<td>0 1</td>
<td>0</td>
<td>1</td>
<td>Q(t)</td>
</tr>
<tr>
<td>1 0</td>
<td>0</td>
<td>1</td>
<td>Q(t)</td>
</tr>
<tr>
<td>1 1</td>
<td>1</td>
<td>1</td>
<td>0</td>
</tr>
</tbody>
</table>

- Note that when CK is 0, the simple latch has both inputs 0 and the inputs S and R have no effect
Gated Latch Transition Table

Note that the internal latch inputs will both go from 1 to 0 if the S and R inputs are both 1 when the clock goes low. Hence we must never have S and R at 1 when the clock is 1.

We make the following rules for changing inputs:

- Don't change the inputs while the clock is asserted.
- Don't apply the inputs $S = R = 1$ when the clock is asserted.

Then we can use the following model of latch behavior:

- While the clock is not asserted, the inputs are ignored and the state does not change.
- When the clock is asserted, the latch can change state and the values of the input signals $S(t)$ and $R(t)$ and current state $Q(t)$ just prior to the clock assertion determine the new value of the latch's state $Q(t+1)$.

Assuming this model, we can describe the latch's behavior by a table that gives the new state $Q(t+1)$ that will occur when the clock is asserted given the current state $Q(t)$ and the current inputs $S(t)$ and $R(t)$.

<table>
<thead>
<tr>
<th>$S(t)$</th>
<th>$R(t)$</th>
<th>$Q(t)$</th>
<th>$Q(t+1)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

This table is called a transition table or state transition table.

The clock is not shown explicitly, but is inherent in the interpretation we place on table.

Gated D Latch

This latch is useful when you need a device to store (remember) a bit of data.

The $D$ stands for "data" or "delay."

- The term data refers to the fact that the latch stores data.
- The term delay refers to the fact that the output $Q$ is equal to the input $D$ one time period later. That is, $Q$ is equal to $D$ delayed by one time period.

Gated D Latch Transition Table

<table>
<thead>
<tr>
<th>$D(t)$</th>
<th>$Q(t)$</th>
<th>$Q(t+1)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

There is no such thing as an ungated D latch. Why?

The gated D latch is also called a transparent latch.
Alternative Design of the gated D Latch

Exercise: Compare this implementation with the following one:

Propagation Delay of Gated Latches

Since changes in the data inputs of a gated latch have no effect unless the clock is asserted, propagation delay is not measured from the data inputs.

Propagation delay is measured from the clock input to the outputs.

- \( t_{PCQ} \) (or \( t_{PQ} \)) - delay from time clock is asserted until the Q output changes

- \( t_{PCQ_L} \) (or \( t_{PQ_L} \)) - delay from time clock is asserted until the \( Q_L \) output changes

Propagation delays can be different from high-to-low transition and low-to-high transitions.
Verilog description of gated latches

- **Gated SR Latch:**

  ```verilog
  module gatedsr (G, S, R, Q);
  input G, R, S;
  output Q;
  reg Q;

  always @(G or S or R)
  if (G)
    if (S & ~R) Q = 1;
    else if (~S & R) Q = 0;
    else if (S & R) Q = 0;
  endmodule
  ``

- **Gated D Latch:**

  ```verilog
  module gatedd (D, Clk, Q);
  input D, Clk;
  output Q;
  reg Q;

  always @(D or Clk)
  if (Clk)
    Q = D;
  endmodule
  ``

Exercise

- **Consider the following 4-stage shift register made from gated D latches:**

  ![4-stage shift register diagram]

  The intended behavior is that data bits are shifted in at the DIN terminal and shifted out at the Q4 terminal four clock pulses later. The first clock pulse loads the bit into Q1 and the second clock pulse transfers this bit from Q1 to Q2 while a new bit is loaded into Q1, and so on.

- **What applications could you suggest for this circuit?**
Draw a timing diagram for this circuit assuming that the propagation delay of the latch is greater than the clock pulse width.

Draw a timing diagram for this circuit assuming that the propagation delay of the latch is less than the clock pulse width.

Flip-Flops

Dynamic Clock Inputs

- The gated latch only looks at its data inputs while the clock is asserted; it ignores them at other times.
  - The window of time when the latch is looking at and reacting to its inputs is the duration of the time that the clock is asserted.

- It is easier to design the circuits that generate a latch’s data inputs if the window when the latch is looking at the data inputs is small.
  - We could only assert the clock for a short time, but this creates other problems.

- Dynamic clock inputs and the latches that use them reduce the window to a very small time around an edge of the clock.

- There are two types of dynamic clock inputs, *edge-triggered* and *master-slave*.

- Latches that use dynamic clocks are called *flip-flop*.
Positive Edge-Triggered D Flip-Flops

- This flip-flop samples its D input on the rising edge of the clock and is therefore called an edge-triggered flip-flop.
- The first latch is called the master latch and the second one is called the slave latch. The slave latch always follows the master latch.
- Note that Brown & Vranesic call this a master-slave flip-flop.

Edge-triggered flip-flop behavior

- When the clock is low, the master latch is enabled and its output follows its D input. When the clock makes a low-to-high transition, the master latch is deactivated and the last value it saw in its D input is stored in its memory. At the same time, this value is transferred from the master to the slave latch.
- The slave is enabled while the clock is high, it will only change its value at the time the clock goes high, since its input is connected to the master, and it cannot change while the clock is high.
- The edge-triggered flip-flop behaves as if it samples its input during rising edges of the clock, and that is the only time its output can change.
- The sampling window is very short, and that is the only time during which the input signal must be held constant.
**Negative Edge-Triggered D Flip-Flops**

![Logic Diagram Symbol]

**Asynchronous Inputs**

- If CLK is held at 0, the D flip-flop acts like an SR latch with PR the set input and CLR the reset input.

**Edge-Triggered JK Flip-Flops**

- The JK Flip-Flop has two inputs J and K. All four possible input configurations are valid. The J acts like S and the K acts like R, when there is only one input with value 1. When both J and K are 1, the flip-flop toggles.

![Logic Diagram Symbol]

- What would happen if we used a gated D latch instead of an edge triggered flip-flop?
Verilog descriptions of edge-triggered flip-flops

- D Flip-Flop

```verilog
module flipflopD (D, Ck, Clr, Q);
input D, Ck, Clr;
output Q;
reg Q;

always @(posedge Ck or posedge Clr)
if (Clr) Q = 0;
else Q = D;
endmodule
```

- JK Flip-Flop

```verilog
module flipflopJK (Ck, J, K, Q);
input Ck, J, K;
output Q;
reg Q;

always @(negedge Ck)
if (J & ~K) Q = 1;
else if (~J & K) Q = 0;
else if (J & K) Q = ~Q;
endmodule
```

Timing parameters for edge-triggered flip-flops

- Inputs must not change while they are being sampled by the clock.
  - Setup and hold times
    - Sampling Window
    - t_{su} - Setup time
    - t_{hl} - Hold time
  - Propagation delays
    - t_{PLH(CQ)}
    - t_{PHL(CQ)}

- Propagation delay must exceed hold time!
**Trigger Flip-Flop**

- Logic Diagram
- Symbol

**Master-Slave Flip-Flops**
- SR master-slave flip-flop
- Logic Diagram
- Symbol
- JK master-slave flip-flop
- Logic Diagram
- Symbol

**Pulse Catching**

- CK
- J
- K
- QM
- GS

**Comparison of flip-flop types**

- S
- QL
- QMS
- QET
- CK
- S
- R
- QL
- QMS
- QET
Verilog description of master-slave flip-flops

```verilog
module flipflopms (Ck, S, R, Q, master);
input Ck, S, R;
output Q, master;
reg master, Q;

always @(Ck or S or R)
if (Ck) begin
  if (S & ~R) master = 1;
  else if (~S & R) master = 0;
  else if (S & R) master = 0;
end
else
  Q = master;

endmodule
```

Review

- The behavior of latches
  - Metastability
- Adding clocks to latches - gated latches
- The properties of dynamic clocks - flip-flops
  - Edge-triggering
  - Setup and Hold times
- Types of flip-flops:
  - SR, D and JK
- The transition table model for flip-flop behavior